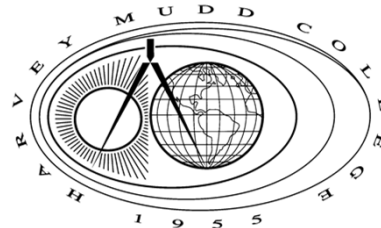


# Introduction to CMOS VLSI Design

## Lecture 9: Circuit Families

David Harris



Harvey Mudd College

Spring 2004

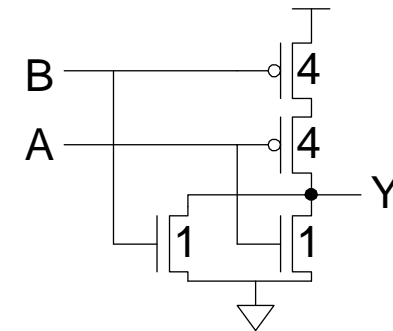
# Outline

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- Pseudo-nMOS Logic
- Dynamic Logic
- Pass Transistor Logic

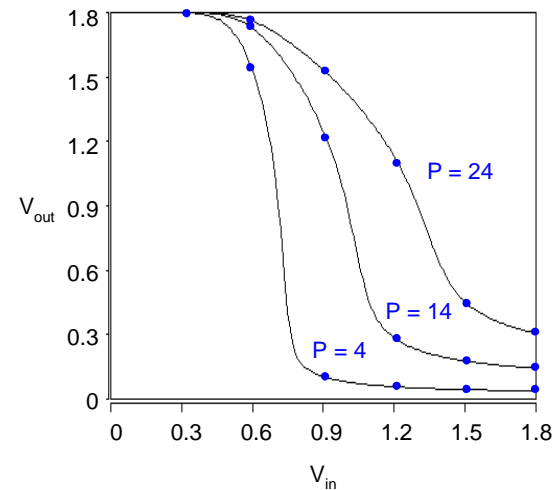
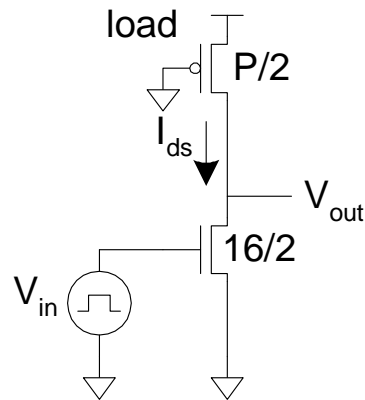
# Introduction

- ❑ What makes a circuit fast?
  - $I = C \, dV/dt \quad \rightarrow \quad t_{pd} \propto (C/I) \, \Delta V$
  - low capacitance
  - high current
  - small swing
- ❑ Logical effort is proportional to  $C/I$
- ❑ pMOS are the enemy!
  - High capacitance for a given current
- ❑ Can we take the pMOS capacitance off the input?
- ❑ Various circuit families try to do this...



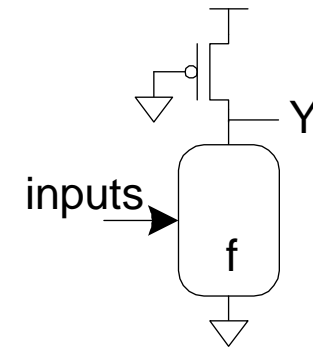
# Pseudo-nMOS

- ❑ In the old days, nMOS processes had no pMOS
  - Instead, use pull-up transistor that is always ON
- ❑ In CMOS, use a pMOS that is always ON
  - *Ratio* issue
  - Make pMOS about  $\frac{1}{4}$  effective strength of pulldown network

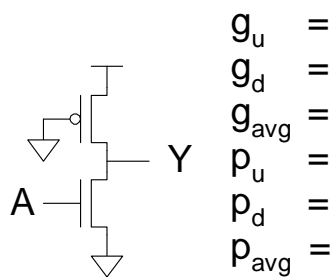


# Pseudo-nMOS Gates

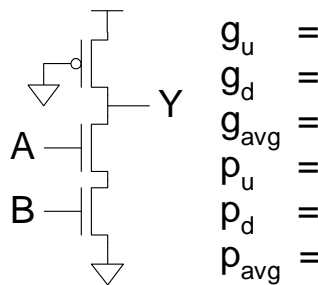
- Design for unit current on output to compare with unit inverter.
- pMOS fights nMOS



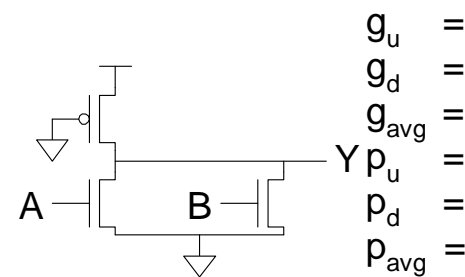
Inverter



NAND2

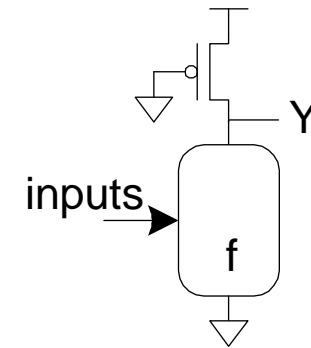


NOR2

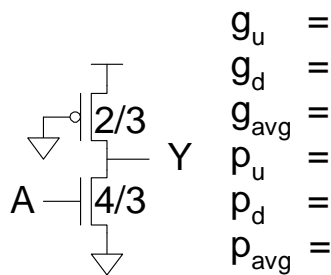


# Pseudo-nMOS Gates

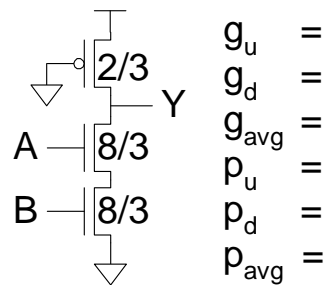
- ❑ Design for unit current on output to compare with unit inverter.
- ❑ pMOS fights nMOS



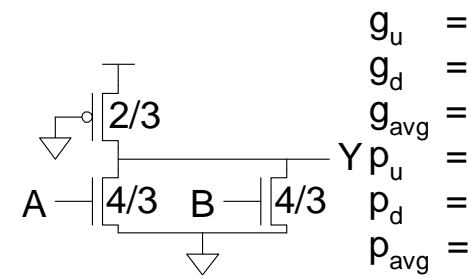
Inverter



NAND2

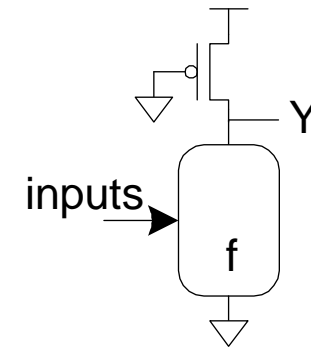


NOR2

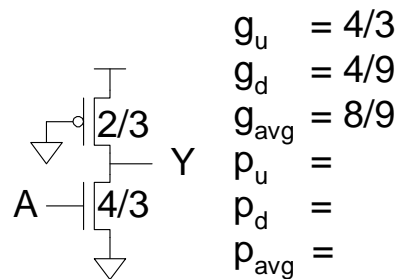


# Pseudo-nMOS Gates

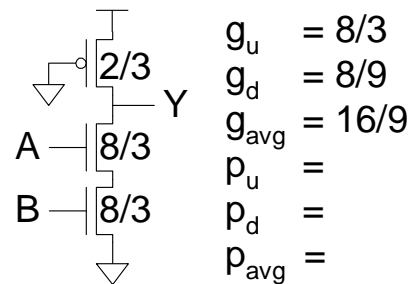
- Design for unit current on output to compare with unit inverter.
- pMOS fights nMOS



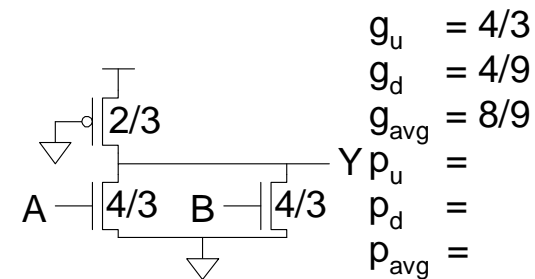
Inverter



NAND2

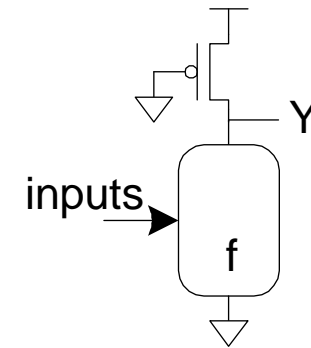


NOR2

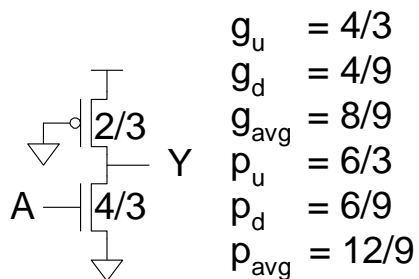


# Pseudo-nMOS Gates

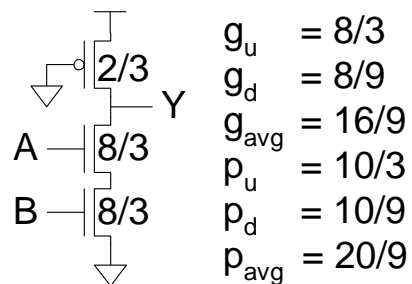
- Design for unit current on output to compare with unit inverter.
- pMOS fights nMOS



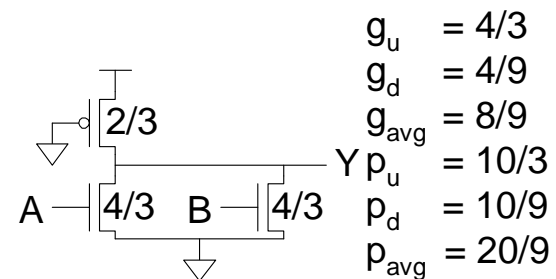
Inverter



NAND2



NOR2

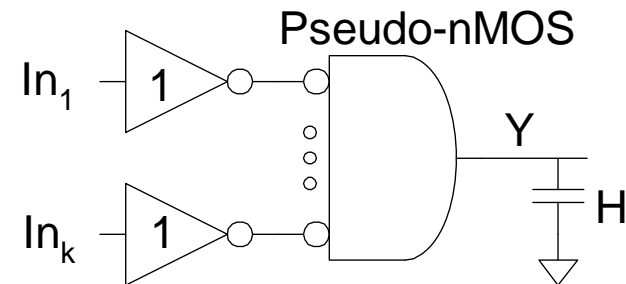




# Pseudo-nMOS Design

- Ex: Design a k-input AND gate using pseudo-nMOS. Estimate the delay driving a fanout of H

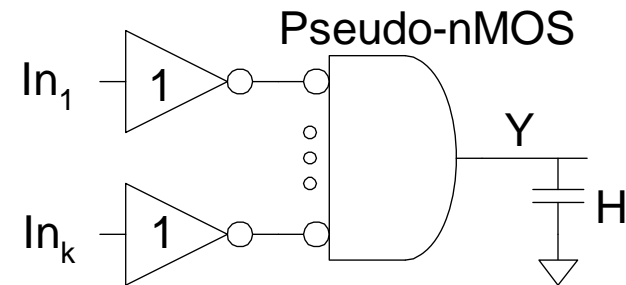
- $G =$
- $F =$
- $P =$
- $N =$
- $D =$



# Pseudo-nMOS Design

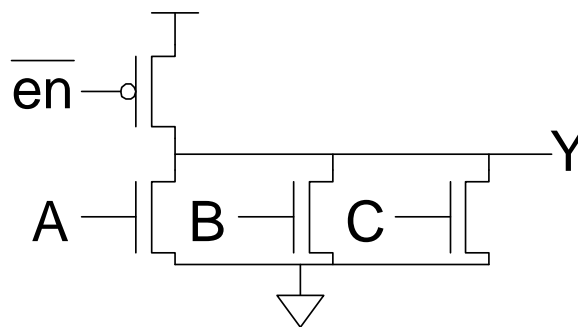
- Ex: Design a k-input AND gate using pseudo-nMOS. Estimate the delay driving a fanout of H

- $G = 1 * 8/9 = 8/9$
- $F = GBH = 8H/9$
- $P = 1 + (4+8k)/9 = (8k+13)/9$
- $N = 2$
- $D = NF^{1/N} + P = \frac{4\sqrt{2H}}{3} + \frac{8k+13}{9}$



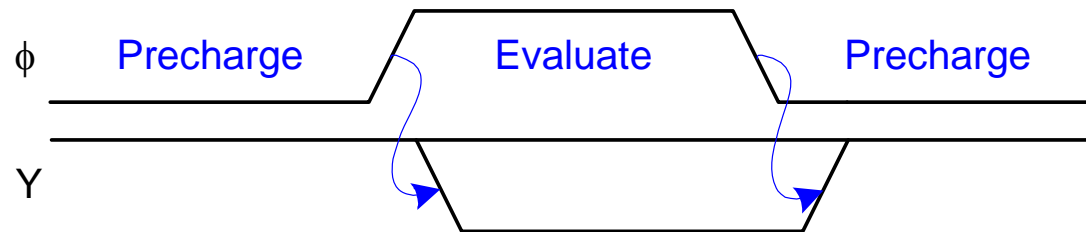
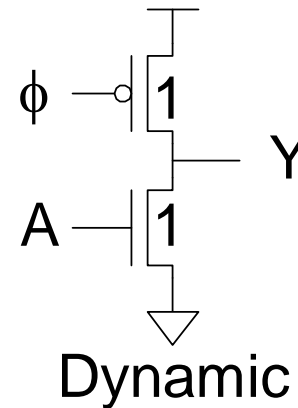
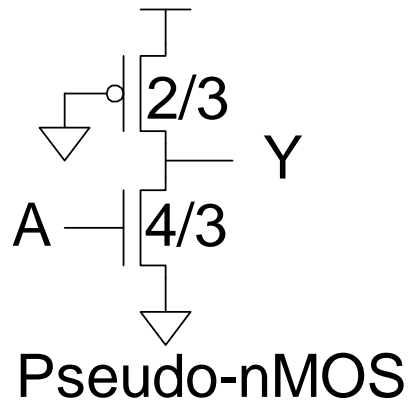
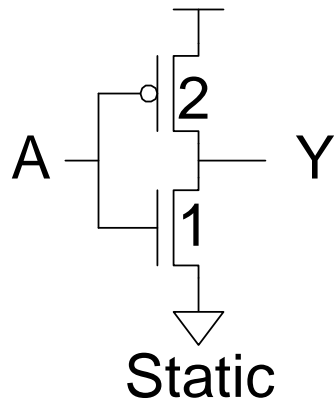
# Pseudo-nMOS Power

- ❑ Pseudo-nMOS draws power whenever  $Y = 0$ 
  - Called static power  $P = I \cdot V_{DD}$
  - A few mA / gate \* 1M gates would be a problem
  - This is why nMOS went extinct!
- ❑ Use pseudo-nMOS sparingly for wide NORs
- ❑ Turn off pMOS when not in use



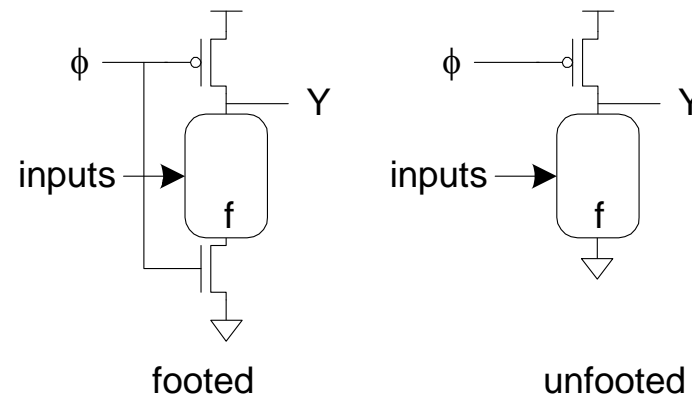
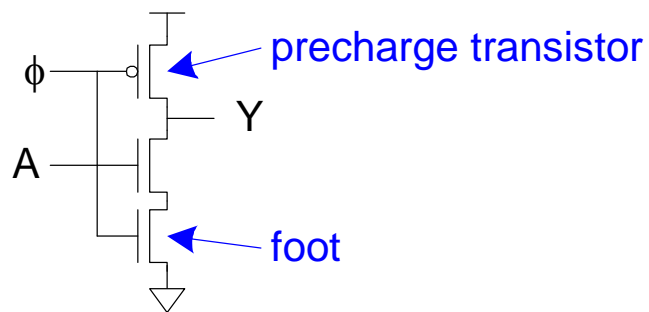
# Dynamic Logic

- ❑ *Dynamic* gates uses a clocked pMOS pullup
- ❑ Two modes: *precharge* and *evaluate*



# The Foot

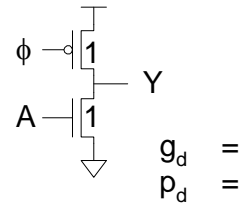
- ❑ What if pulldown network is ON during precharge?
- ❑ Use series evaluation transistor to prevent fight.



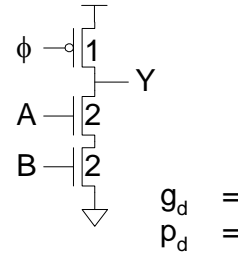
# Logical Effort

unfooted

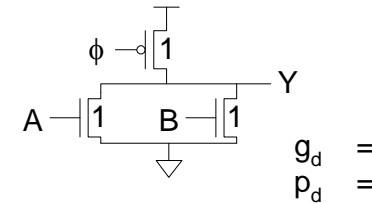
Inverter



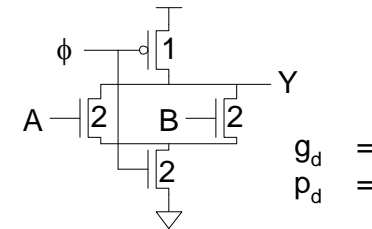
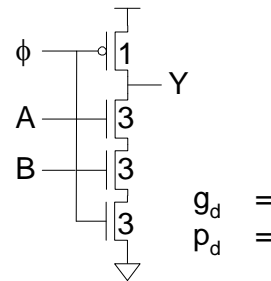
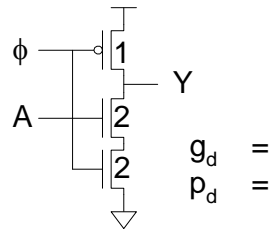
NAND2



NOR2



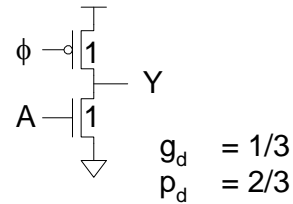
footed



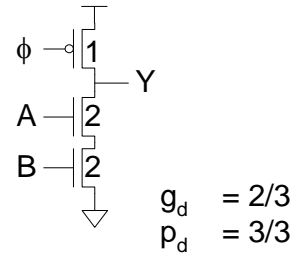
# Logical Effort

unfooted

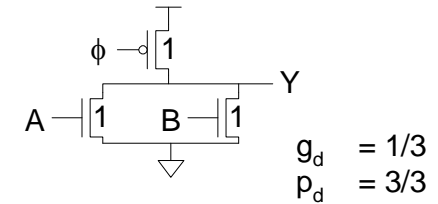
Inverter



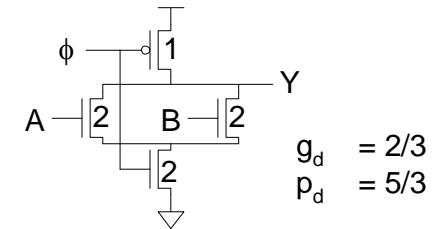
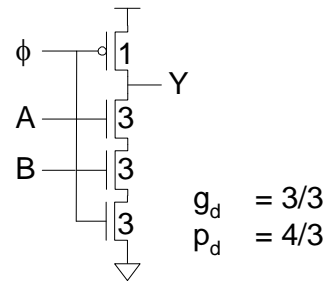
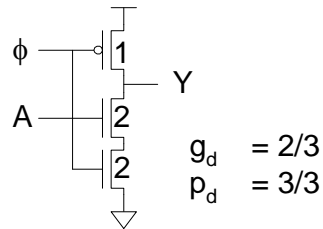
NAND2



NOR2



footed



# Monotonicity

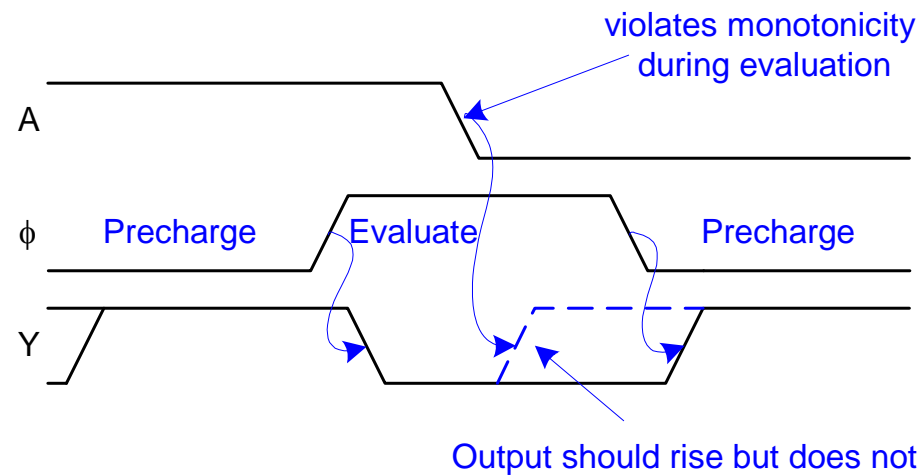
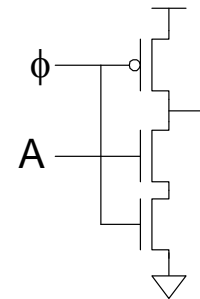
- Dynamic gates require *monotonically rising* inputs during evaluation

- 0 -> 0

- 0 -> 1

- 1 -> 1

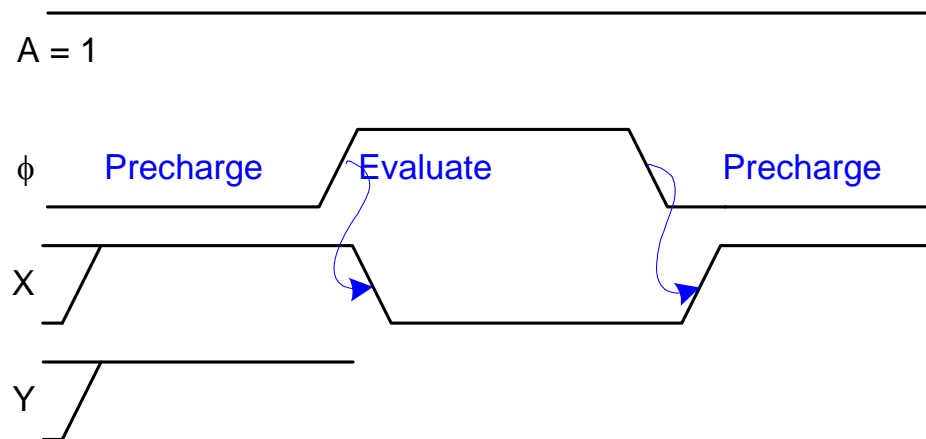
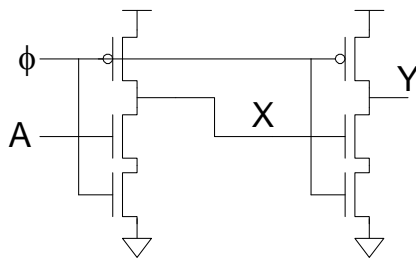
- But not 1 -> 0





# Monotonicity Woes

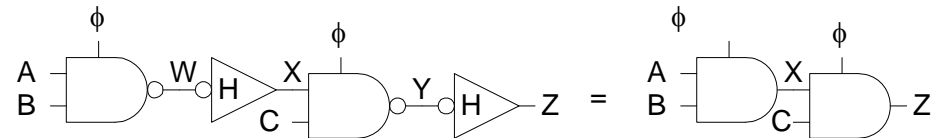
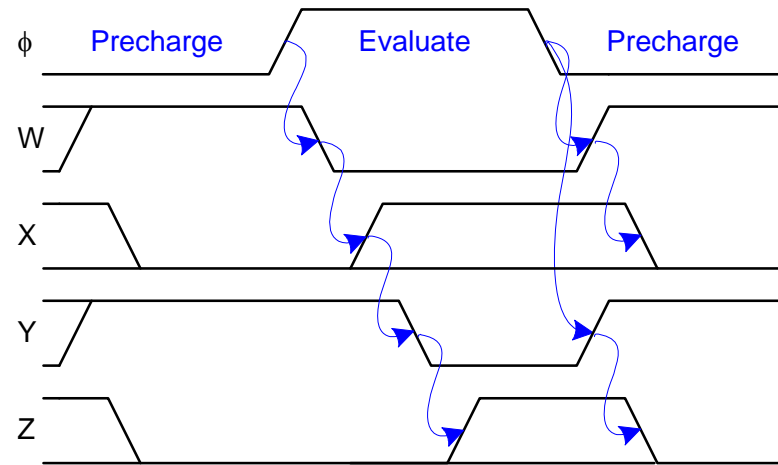
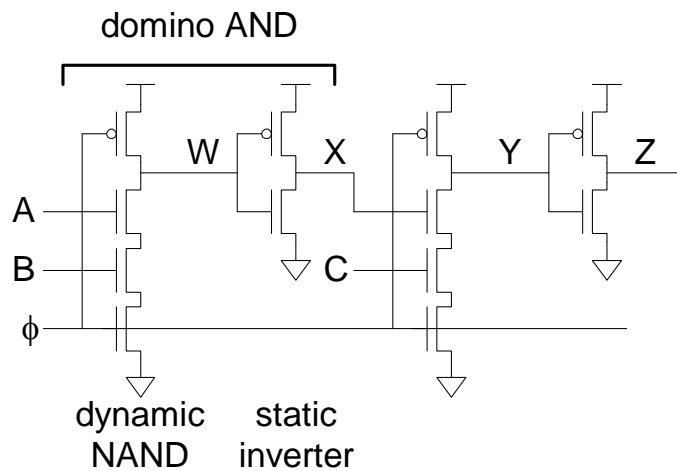
- ❑ But dynamic gates produce monotonically falling outputs during evaluation
- ❑ Illegal for one dynamic gate to drive another!





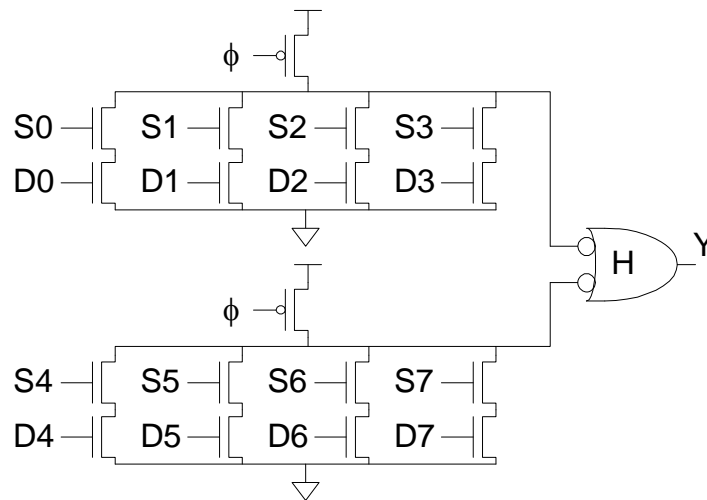
# Domino Gates

- Follow dynamic stage with inverting static gate
  - Dynamic / static pair is called domino gate
  - Produces monotonic outputs



# Domino Optimizations

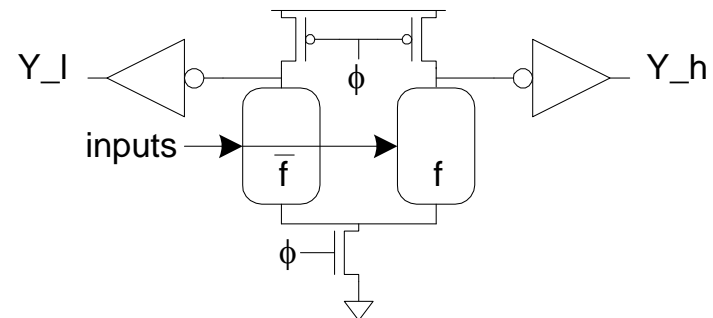
- ❑ Each domino gate triggers next one, like a string of dominos toppling over
- ❑ Gates evaluate sequentially but precharge in parallel
- ❑ Thus evaluation is more critical than precharge
- ❑ HI-skewed static stages can perform logic



# Dual-Rail Domino

- ❑ Domino only performs noninverting functions:
  - AND, OR but not NAND, NOR, or XOR
- ❑ Dual-rail domino solves this problem
  - Takes true and complementary inputs
  - Produces true and complementary outputs

sig_h	sig_l	Meaning
0	0	Precharged
0	1	'0'
1	0	'1'
1	1	invalid



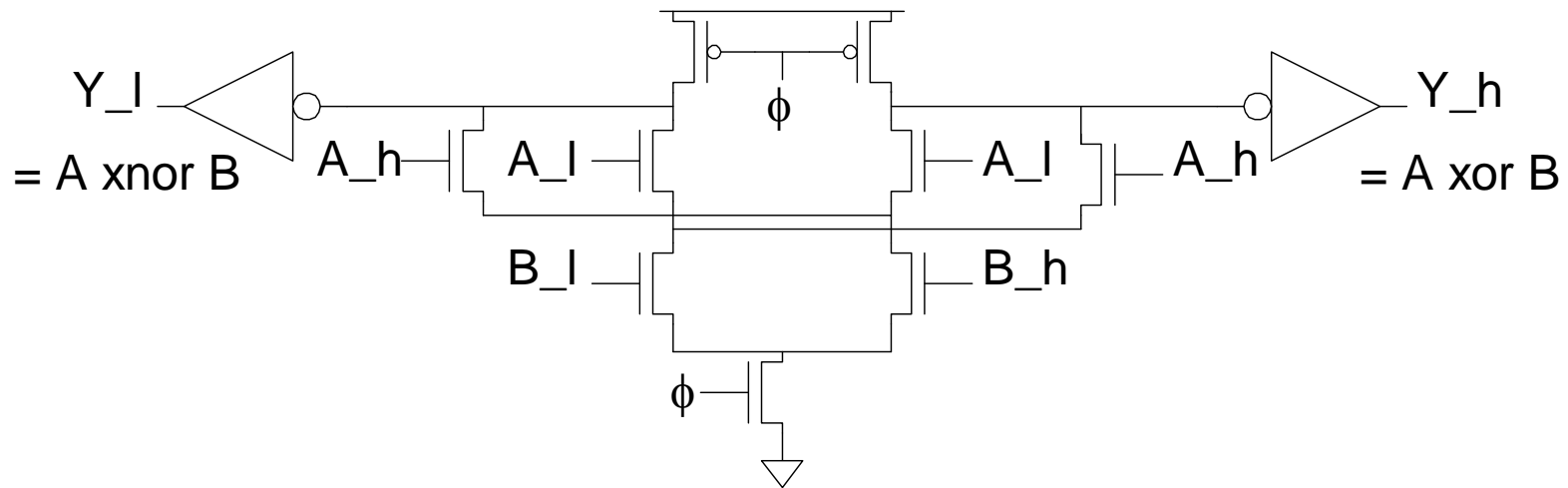
# Example: AND/NAND

- Given  $A_h, A_l, B_h, B_l$
- Compute  $Y_h = A * B, Y_l = \sim(A * B)$



# Example: XOR/XNOR

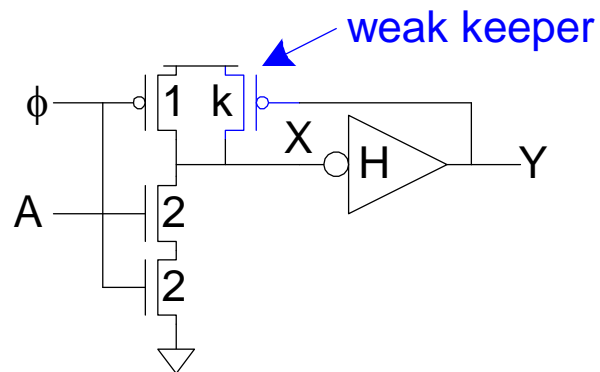
- Sometimes possible to share transistors





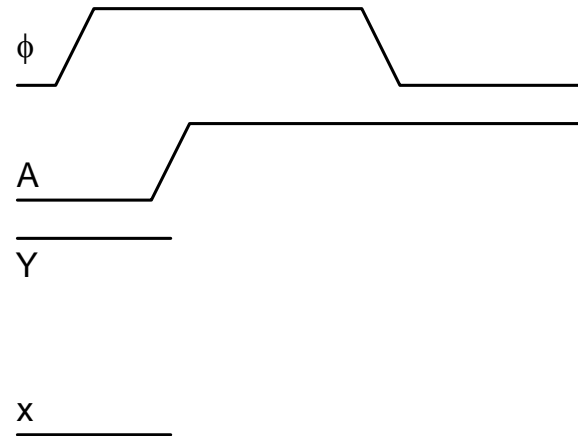
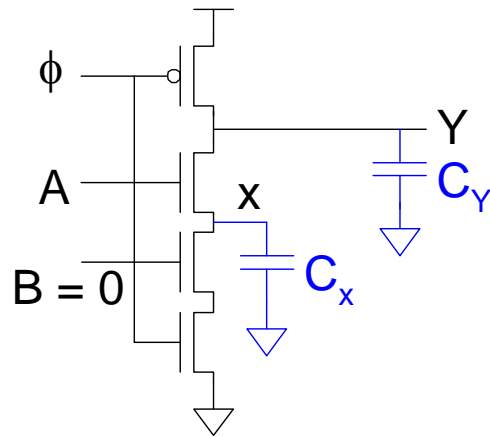
# Leakage

- ❑ Dynamic node floats high during evaluation
  - Transistors are leaky ( $I_{OFF} \neq 0$ )
  - Dynamic value will leak away over time
  - Formerly milliseconds, now nanoseconds!
- ❑ Use keeper to hold dynamic node
  - Must be weak enough not to fight evaluation



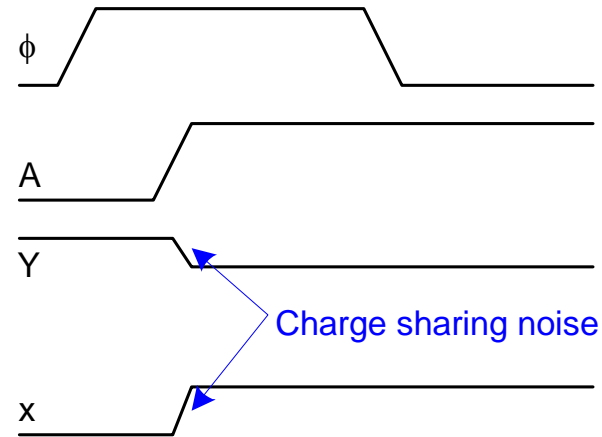
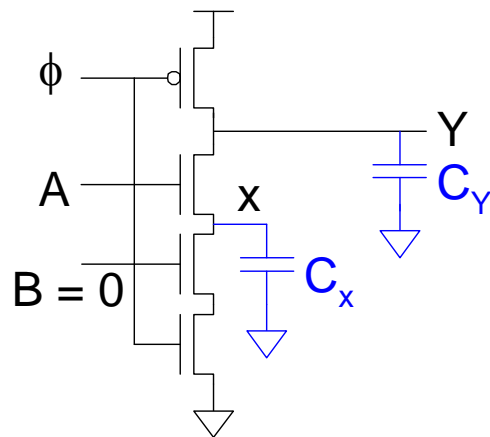
# Charge Sharing

- ❑ Dynamic gates suffer from charge sharing



# Charge Sharing

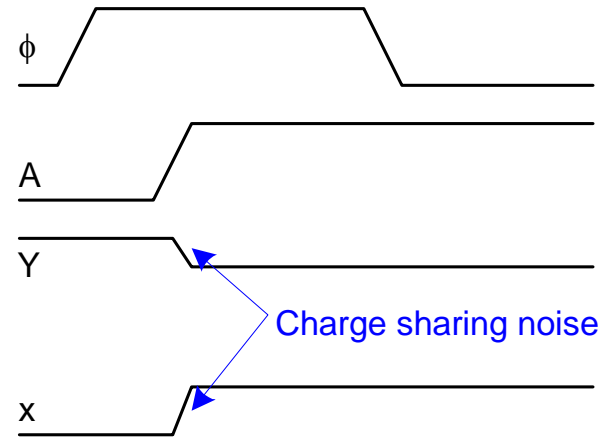
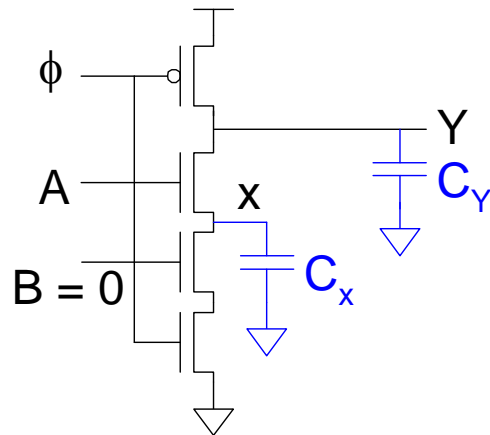
- ❑ Dynamic gates suffer from charge sharing



$$V_x = V_Y =$$

# Charge Sharing

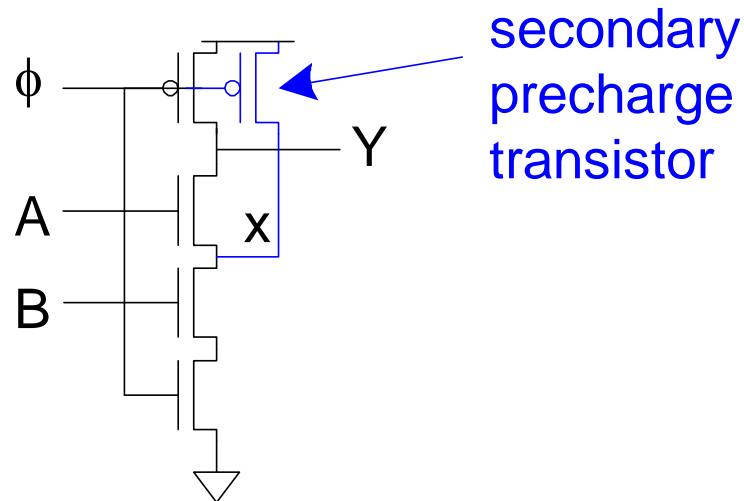
- ❑ Dynamic gates suffer from charge sharing



$$V_x = V_Y = \frac{C_Y}{C_x + C_Y} V_{DD}$$

# Secondary Precharge

- ❑ Solution: add secondary precharge transistors
  - Typically need to precharge every other node
- ❑ Big load capacitance  $C_Y$  helps as well



# Noise Sensitivity

- ❑ Dynamic gates are very sensitive to noise
  - Inputs:  $V_{IH} \approx V_{tn}$
  - Outputs: floating output susceptible noise
- ❑ Noise sources
  - Capacitive crosstalk
  - Charge sharing
  - Power supply noise
  - Feedthrough noise
  - And more!

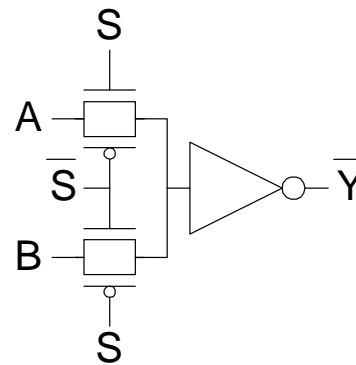
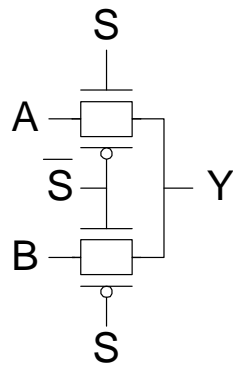
# Domino Summary

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- ❑ Domino logic is attractive for high-speed circuits
  - 1.5 – 2x faster than static CMOS
  - But many challenges:
    - Monotonicity
    - Leakage
    - Charge sharing
    - Noise
- ❑ Widely used in high-performance microprocessors

# Pass Transistor Circuits

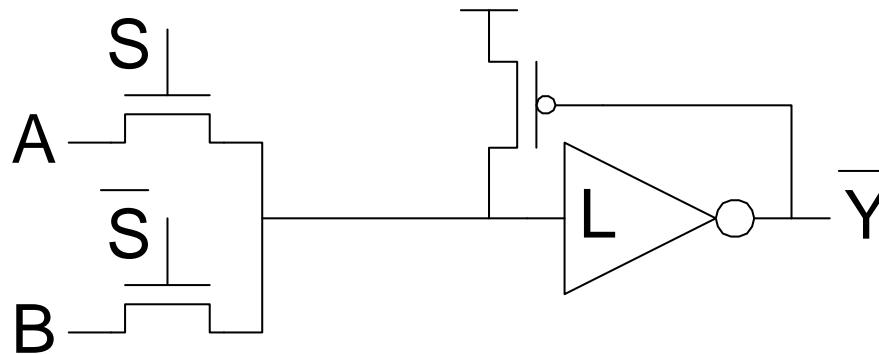
- ❑ Use pass transistors like switches to do logic
- ❑ Inputs drive diffusion terminals as well as gates
- ❑ CMOS + Transmission Gates:
  - 2-input multiplexer
  - Gates should be restoring





# LEAP

- ❑ **LEA**n integration with **P**ass transistors
- ❑ Get rid of pMOS transistors
  - Use weak pMOS feedback to pull fully high
  - Ratio constraint



# CPL

- **C**omplementary **P**ass-transistor **L**ogic
  - Dual-rail form of pass transistor logic
  - Avoids need for ratioed feedback
  - Optional cross-coupling for rail-to-rail swing

